# Submodular Function Maximization via the Multilinear Relaxation and Contention Resolution Schemes

Rico Zenklusen

MIT

Joint work with Chandra Chekuri and Jan Vondrák

# Outline

### 1 Introduction

- **2** General framework
- **3** Maximizing the multilinear extension
- **4** Rounding through contention resolution schemes
- **5** An optimal CR-scheme for matroids
- **6** Conclusions

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## **Submodular functions**

• Let N be a finite ground set, n := |N|.

#### **Definition (submodular function)**

A set function  $f : 2^N \to \mathbb{R}$  is submodular if it has diminishing returns:

$$f(\underbrace{A+i}_{:=A\cup\{i\}}) - f(A) \ge f(B+i) - f(B) \qquad \forall A \subseteq B \subseteq N, \forall i \in N \setminus B$$

Equivalent definition:  $f(A) + f(B) \ge f(A \cup B) + f(A \cap B)$   $\forall A, B \subseteq N$ .

 $\longrightarrow$  Submodularity is a natural property of utility functions.

• f is monotone  $\Leftrightarrow f(A) \leq f(B) \quad \forall A \subseteq B.$ 

## Examples of subm. funct. beyond utility functions

#### Example I: coverage function

Let U be a finite ground set and  $W_i \subseteq U$  for  $i \in N$ .

$$f(A) = \left| \bigcup_{i \in A} W_i \right| \quad \forall A \subseteq N$$



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#### Example II: cut function

Let G = (V, E) be a graph with edge weights  $w : E \rightarrow \mathbb{R}_+$ .

$$f(U) = w(\delta(U)) = w(E(U, V \setminus U)) \ \forall U \subseteq V$$





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#### Other examples

• Entropy function  $H: 2^N \to \mathbb{R}_+$  of random variables  $\{X_i\}_{i \in N}$ :

 $H(A) := H(\{X_i \mid i \in A\}) \quad \forall A \subseteq N.$ 

Reduction of connection costs in facility location problems.

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#### Minimization vs. maximization

- Unconstrained minimization of submodular functions can be done efficiently.
- Unconstrained maximization of submodular functions is hard:
  - Currently best approximation ratio: 0.41. (Oveis Gharan and Vondrák, 2011)
  - No > 0.5-approx without exponentially many calls to value oracle. (Feige et al., 2007)
  - Remains hard in many settings outside the value oracle model (MAX-CUT, MAX-K-COVER, ...).
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- $\Theta(1)$ -approximations often achievable under additional constraints.

Under which constraints is it possible to approximately maximize submodular functions?

## Previous results on SFM (subm. funct. max.)

• Assume  $f : 2^N \to \mathbb{R}_+$  (otherwise: no hope for good approximations).

Approaches for SFM are based either on

- a) combinatorial local search procedures (replacing elements), or
- b) relaxation and rounding techniques.

Constraint type	Linear max.	Monotone subm. max.	Subm. max.
O(1) knapsacks	$1-\epsilon$	$1-1/e-\epsilon^{-1}$	$0.25 - \epsilon^{-1}$
1 matroid	1	$1 - 1/e^{-2}$	0.325 <sup>3</sup>
k = O(1) matroids	$1/(k-1+\epsilon)^{-4}$	$1/(k+\epsilon)^{-4}$	$1/(k+1+\frac{1}{k-1}+\epsilon)^4$

<sup>1</sup>Kulik et al. (2011)
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Issue with previous approaches

Typically heavily tailored to the underlying constraints.

 $\rightarrow$  e.g., despite progress on knapsack and matroid constraints, not much was known about a combination of those constraints.

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#### Is there some more versatile framework?

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### **Our results**

We introduce a rather general relaxation-and-rounding framework that allows for combining constraints (at the price of a slightly weaker approximation quality).

#### (Some) new results due to our framework

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$k$ matr. & $\ell = O(1)$ knaps.	0.6/k	0.38/k	0.19/ <i>k</i>
$k$ -matchoid & $\ell$ -sparse PIP	$\Omega(1/(k+\ell))$	$\Omega(1/(k+\ell))$	$\Omega(1/(k+\ell))$
UFP on paths and trees	$\Omega(1)$	$\Omega(1)$	$\Omega(1)$

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- new results
- previous results

#### Remark

The constraints  $\mathcal{F} \subseteq 2^N$  we consider are all closed under inclusion, i.e.,

 $A \in \mathcal{F}, B \subseteq A \Rightarrow B \in \mathcal{F}.$ 

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#### 1. Create relaxed problem

- i) Relax constraints:  $\mathcal{F} \subseteq 2^N \rightsquigarrow \text{ polytope } P \subseteq [0, 1]^N$
- ii) Extend submodular function:  $f \rightsquigarrow F : [0,1]^N \rightarrow \mathbb{R}_+$ ( $F(\mathbf{1}_S) = f(S) \forall S \subseteq N$ ).
- **2.** Maximize F over  $P \rightsquigarrow x \in P$
- **3. Rounding:**  $x \rightsquigarrow I(x) \in \mathcal{F}$

i) 
$$x \rightsquigarrow R(x) \subseteq N$$
 with

$$\Pr[i \in R(x)] = x_i$$

ii)  $R(x) \rightsquigarrow I(x) \in \mathcal{F}$ , with  $I(x) \subseteq R(x)$  and



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## Shooting for a good extension

• Multilinear extension:  $F(x) := \sum_{S \subseteq N} f(S) \prod_{i \in S} x_i \prod_{i \in N \setminus S} (1 - x_i) = E[f(R(x))]$ , where

 $R(x) \subseteq N$ : random set with  $\Pr[i \in R(x)] = x_i$  independently for  $i \in N$ .

- Easy to approximately evaluate through Monte-Carlo sampling.
- Behaves nicely w.r.t. indep. rounding (would lead to constraint violations).

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- Easy to approximately evaluate through Monte-Carlo sampling.
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► Lovász extension: 
$$f^{L}(x) := \min \left\{ \sum_{S \subseteq N} \alpha_{S} f(S) \middle| \sum_{S \subseteq N, i \in S} \alpha_{S} = x_{i}, \sum_{S \subseteq N} \alpha_{S} = 1, \alpha_{S} \ge 0 \right\}$$

- Convex
- Easy to evaluate
- Hard to maximize

• Concave closure:  $f^+(x) := \max\left\{ \left. \sum_{S \subseteq N} \alpha_S f(S) \right| \sum_{S \subseteq N, i \in S} \alpha_S = x_i, \sum_{S \subseteq N} \alpha_S = 1, \alpha_S \ge 0 \right\}$ 

- Concave
- Hard to evaluate

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# Maximizing F over solvable down-closed polytopes P

#### Definitions

- ▶ *P* is down-closed (or down-monotone) if  $x \in P, y \le x \Rightarrow y \in P$ .
- ► *P* is solvable if linear functions can be optimizing efficiently over *P*.

#### Our main results here

- We can find  $y \in P$  with  $F(y) \ge 0.25 \cdot \max\{F(x) \mid x \in P\}$ .
- We can find  $y \in P$  with  $F(y) \ge 0.325 \cdot \max\{F(x) \mid x \in P \cap \{0,1\}^N\}$ .
- ▶ Next slides: very short sketch of the 0.25-approx due to its simplicity.
- To get some intuition let's first consider a related 1/3-approx for unconstrained SFM (which is a variation of an algo of Feige et al. (2007)).

# Getting some intuition

A related 1/3-approx for unconstrained SFM

### $\frac{1}{2}$ -approx for unconstrained SFM

- **1.** Find a local opt  $X \subset N$ :

```
f(X \pm i) \leq f(X) \quad \forall i \in \mathbb{N}.
2. Find a local opt Y \subseteq N \setminus X: f(Y \pm i) \leq f(Y) \quad \forall i \in N \setminus X.
```

3. Return the better of X and Y.

#### Proof.

- Let Z be a global opt.
- X local opt:
  - $f(X) \geq f(X \cup Z)$ , •  $f(X) > f(X \cap Z)$ .
- Y local opt:
  - $f(Y) > f(Y \cup (Z \setminus X)).$





## Sketch of the 0.25-approx for down-closed P

### 0.25-approx

1. Find an (approximate) local opt x of F over P, i.e.,

$$abla F(x) \cdot (v-x) \leq 0 \quad \forall v \in P.$$

- 2. Find an (approximate) local opt y of F over  $Q = \{v \in P \mid v \le 1 x\}$ ,  $\nabla F(y) \cdot (v - y) \le 0 \quad \forall v \in Q.$
- **3.** Return the better of x and y.

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# Contention resolution (CR) schemes

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### Plan: accept lower value for expectation to obtain feasibility,

maintain "sufficient" independence in rounding process to get good expectation.

#### Definition: balanced CR scheme

A *c*-balanced CR scheme for *P* is a (random) procedure parametrized by  $x \in P$ , that selects a set  $I \in \mathcal{F}$ ,  $I \subseteq R(x)$  with

$$\Pr[i \in I] \ge c \cdot x_i \quad \Leftrightarrow \quad \Pr[i \in I \mid i \in R(x)] \ge c \qquad \forall i \in N$$

Furthermore, the scheme is called

monotone if

$$\Pr[i \in I \mid R(x) = R_1] \ge \Pr[i \in I \mid R(x) = R_2] \qquad \forall i \in R_1 \subseteq R_2 \subseteq N_2$$

and strict if

$$\Pr[i \in I \mid i \in R(x)] = c \quad \forall i \in N.$$

## **Rounding guarantees**

### Theorem (follows from Bansal et al. (2010))

Let  $x \in P$ , and let I(x) be the output of a monotone and strict *c*-balanced CR scheme. Then

 $\mathbf{E}[f(I(x))] \ge c \cdot F(x).$ 

## **Rounding guarantees**

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#### Remarks

- Strictness is only needed for non-monotone f, and can be avoided by a simple post-processing of I.
- The rounding procedure is oblivious to *f*.

### Proof of rounding guarantee (I)

- We number the elements  $N = [n] := \{1, \ldots, n\}$ .
- ▶ For  $A \subseteq N$ ,  $i \in N$ , let  $f_A(i) = f(A+i) f(A)$ .

$$\mathbf{E}[f(I)] = f(\emptyset) + \sum_{i=1}^{n} \mathbf{E}\left[f(I \cap [i]) - f(I \cap [i-1])\right].$$
  
want to show: 
$$\mathbf{E}[f(I \cap [i]) - f(I \cap [i-1])] \ge \Pr[i \in R] \cdot c \cdot \mathbf{E}[f_{R \cap [i-1]}(i)]$$

This then implies

We

$$f(\emptyset) + \sum_{i=1}^{n} \mathbf{E}[f(I \cap [i]) - f(I \cap [i-1])] \ge c \left[ f(\emptyset) + \sum_{i=1}^{n} \Pr[i \in R] \mathbf{E}[f_{R \cap [i-1]}(i)] \right]$$
$$= c \left[ f(\emptyset) + \sum_{i=1}^{n} \mathbf{E}[f(R \cap [i]) - f(R \cap [i-1])] \right]$$
$$= c \cdot F(x).$$

# Proof of rounding guarantee (II)

To show:  $|\mathbf{E}[f(I \cap [i]) - f(I \cap [i-1])] \ge \Pr[i \in R] \cdot c \cdot \mathbf{E}[f_{R \cap [i-1]}(i)]$ 

$$\begin{aligned} \mathbf{E}[f(I \cap [i]) - f(I \cap [i-1])] &= \mathbf{E}[\mathbf{1}_{i \in I} f_{I \cap [i-1]}(i)] \\ &\geq \mathbf{E}[\mathbf{1}_{i \in I} f_{R \cap [i-1]}(i)] \\ &\geq \mathbf{E}_{R}[\mathbf{E}_{I}[\mathbf{1}_{i \in I} f_{R \cap [i-1]}(i) \mid R]] \\ &= \mathbf{E}_{R}[\mathbf{E}_{I}[\mathbf{1}_{i \in I} \mid R] f_{R \cap [i-1]}(i)] \\ &\geq \Pr[i \in R] \cdot \mathbf{E}[\Pr[i \in I \mid R] f_{R \cap [i-1]}(i) \mid i \in R] \end{aligned}$$

On the product space associated with distribution of *R* conditioned on  $i \in R$ :

- ▶  $Pr[i \in I \mid R]$  is non-decreasing  $\leftarrow$  monotonicity of CR scheme,
- $f_{R\cap[i-1]}(i)$  is non-decreasing  $\leftarrow$  submodularity of f.
- $\Rightarrow$  we can apply FKG.

 $\begin{aligned} \mathbf{E}_{R}[\Pr[i \in I \mid R] f_{R \cap [i-1]}(i) \mid i \in R] \\ & \stackrel{FKG}{\geq} \mathbf{E}_{R}[\Pr[i \in I \mid R] \mid i \in R] \cdot \mathbf{E}_{R}[f_{R \cap [i-1]}(i) \mid i \in R] \\ & = \Pr[i \in I \mid i \in R] \cdot \mathbf{E}[f_{R \cap [i-1]}(i)] \\ & \stackrel{strictness}{=} c \cdot \mathbf{E}[f_{R \cap [i-1](i)}]. \end{aligned}$
Often,  $\mathcal{F}$  is composed of simpler constraints:  $\mathcal{F} = \mathcal{F}_1 \cap \mathcal{F}_2 \implies P = P_1 \cap P_2$ .

**Goal**: combine monotone (and strict)  $c_1$ -balanced CR scheme for  $P_1$  with monotone (and strict)  $c_2$ -balanced CR scheme for  $P_2$  to obtain one for P.

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Monotonicity is preserved.

Resulting CR scheme is c1 c2-balanced:

 $\Pr[i \in I \mid i \in R(x)] = \mathbf{E}[\mathbf{1}_{i \in I_1} \mathbf{1}_{i \in I_2} \mid i \in R(x)] \stackrel{FKG}{\geq} \underbrace{\mathbf{E}[\mathbf{1}_{i \in I_1} \mid i \in R(x)]}_{\mathbf{E}[\mathbf{1}_{i \in I_2} \mid i \in R(x)]} \underbrace{\mathbf{E}[\mathbf{1}_{i \in I_2} \mid i \in R(x)]}_{\mathbf{E}[\mathbf{1}_{i \in I_2} \mid i \in R(x)]}$ 

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 $=c_2$ 

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- Combining k schemes being c-balanced  $\rightarrow c^k$ -balanced scheme.
- Our goal: obtain  $\Omega(1/k)$ -balanced CR scheme.

**Definition:** (b, c)-balanced **CR** scheme  $(b, c \in (0, 1])$ 

A (b, c)-balanced CR scheme for P is a (random) procedure parametrized by  $x \in P$ , that selects a set  $I \in \mathcal{F}$ ,  $I \subseteq R(b \cdot x)$  with

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This approach is stronger in the parallel part.

• Resulting scheme is  $(b, c_1c_2)$ -balanced.

### Existence of strong CR scheme

#### **Results on CR schemes**

- (b, 1-e<sup>-b</sup>/b)-balanced, monotone and strict CR scheme for matroid constraint, for b ∈ (0, 1]. This scheme is optimal.
- For any fixed ε > 0: (1 − ε, 1 − ε)-balanced monot. and strict CR scheme for knapsack constraint.
- $(b, 1 \Omega(b))$ -balanced, monotone and strict CR scheme for UFP.
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#### Putting the pieces together to obtain the claimed results

E.g. to optimize over k matroid constraints and a  $\ell=\Omega(1)$  knapsacks, a c-balanced CR scheme can be obtaind for

$$c = b \cdot \underbrace{\left(\frac{1 - e^{-b}}{b}\right)^k}_{\text{matroids}} \cdot \underbrace{\left(1 - \epsilon\right)^\ell}_{\text{knapsacks}} \stackrel{b = 1/k}{=} \Omega(1/k).$$

 $\Rightarrow \alpha \cdot \Omega(1/k) = \Omega(1/k)$ -approx to maximize f over those constraints, where  $\alpha = 0.325$  is the approximation ratio for maximizing F over P.

#### Outline

#### **1** Introduction

- **2** General framework
- **3** Maximizing the multilinear extension
- **4** Rounding through contention resolution schemes
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- **6** Conclusions

#### Very short introduction to matroids I

**Definition: Matroid** A matroid  $M = (N, \mathcal{F})$  consists of a finite ground set N and a non-empty family  $\mathcal{F} \subseteq 2^N$  of subsets of N such that:

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i) If I \in \mathcal{F} and J \subseteq I, then J \in \mathcal{F}.
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ii) If I, J \in \mathcal{F} and |I| > |J|, then \exists i \in I \setminus J with J \cup \{i\} \in \mathcal{F}.
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► The sets in *F* are called independent sets and are typically described by an independence oracle.

Maximal independent sets are called bases.

ightarrow Because of *ii*) all bases of a matroid have the same cardinality.

#### Example: graphic matroid

Let G = (V, E) be an undirected graph. The graphic matroid of G is defined to be M = (E, F), where F is the set of all forests of G.

Greedy algorithm finds a maximum weight independent set.

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#### Very short introduction to matroids II

The rank function  $r: 2^N \to \mathbb{Z}_+$  of a matroid  $M = (N, \mathcal{F})$  is defined by:

 $r(A) = \max\{|I| \mid I \subseteq A, I \in \mathcal{F}\}$ 

(BTW, this function is also submodular)

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	max	С			
(I P1)	s.t.	$\sum_{\pi\in\Pi} q_{i,\pi}\lambda_{\pi}$	$\geq$	X <sub>i</sub> C	$\forall i \in N$
( [ ] ]		$\sum_{\pi \in \Pi} \lambda_{\pi}$	=	1	
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• Goal: find  $\pi \in \Pi$  maximizing

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- We want to show that optimal dual value is  $\geq 1 e^{-1}$ .

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- We want to show that optimal dual value is  $\geq 1 e^{-1}$ .
- This is optimal: easy to find examples showing that ∄ (1 − e<sup>-1</sup> − ε)-balanced CR scheme. (e.g. uniform matroid of rank one with x<sub>i</sub> = 1/n for i ∈ N)

#### **Proof procedure**

We show that for any dual-feasible  $y \in [0,1]^N$ ,  $\exists \pi \in \Pi$  with  $\sum_{i \in N} q_{i,\pi} y_i \ge 1 - e^{-1}$ .

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Let y ∈ [0, 1]<sup>N</sup> be dual-feasible, we choose π ∈ Π to be the greedy algorithm w.r.t. the weights y.

$$\sum_{i\in N} q_{i,\pi} y_i = \mathsf{E}\left[\sum_{i\in \pi(R(x))} y_i\right] = \mathsf{E}[r_y(R(x))],$$

where  $r_y$  is the y-weighted rank function of the underlying matroid.

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Theorem (Calinescu et al., 2007; Vondrák, 2007)

Let  $r_w : 2^N \to \mathbb{R}_+$  be the weighted rank function of a matroid  $M = (N, \mathcal{I})$ , with weights  $w : N \to \mathbb{R}_+$ , and let  $v \in P_M$  be a point in the matroid polytope. Then

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- Hence, the optimal dual value is at least  $1 e^{-1}$ .
- ▶  $\Rightarrow \exists$  a  $(1 e^{-1})$ -balanced and monotone CR-scheme for matroids.

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#### Conclusions

- The multilinear extension can be maximized up to a constant factor on any down-closed and solvable polytope.
- Contention resolution schemes provide a modular way for rounding a fractional point in the context of SFM.
- ▶ What is the best possible approximation ratio for maximizing *F* over *P*?
- Convex combinations of monotone deterministic CR schemes are in general not as powerful as randomized CR schemes. How much do we lose?
- What about other extensions than the multilinear one?
- Derandomization?

# Thank you!
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